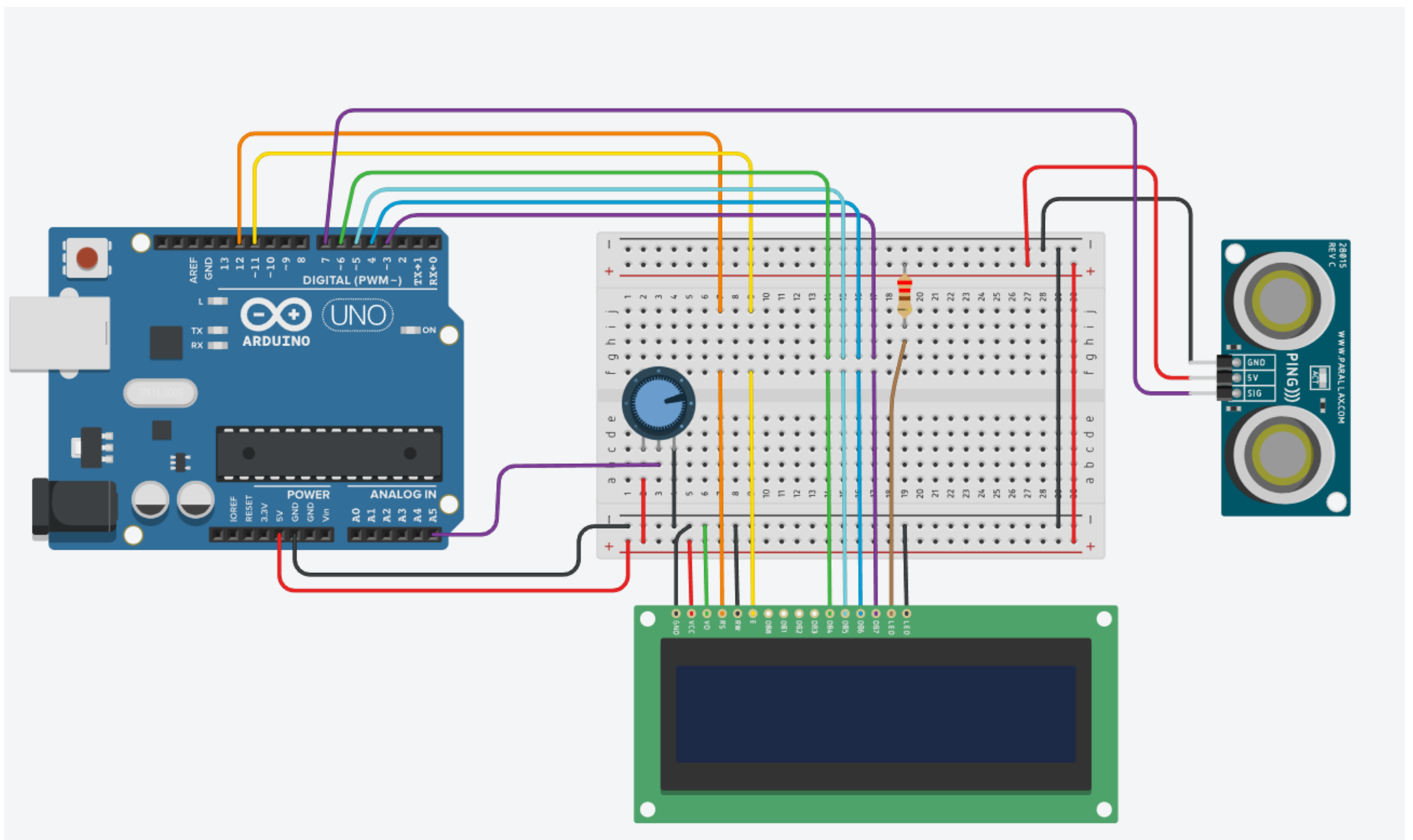


# CONTATORE PEZZI CON SENSORE ULTRASUONI



```
// include libraries:
#include <LiquidCrystal.h>

// initialize the library with the numbers of the interface pins
LiquidCrystal lcd(12, 11, 6, 5, 4, 3);

int state= 0; // pezzo non presente
int laststate=0; // pezzo non presente
int counter= 0;
//int cm = 0;

void setup()
{
  Serial.begin(9600);
  // set up the LCD's number of columns and rows:
  lcd.begin(16, 2);
  lcd.print("READY");
}
```

```

void loop() {
  // rilevamento fronte di discesa segnale sensore
  if (state==1 && laststate==0) {
    counter++;
    Serial.print(counter); Serial.println(" pezzi");

    lcd.clear();
    lcd.setCursor(0, 0); lcd.print("Pezzi");
    lcd.setCursor(0, 1); lcd.print(counter);
  }
  laststate = state; // aggiornamento ultimo stato

  state= readUltrasonicState(7, 7);
  delay(100); // Wait for 100 milliseconds
}

int readUltrasonicState(int triggerPin, int echoPin)
{
  int stato_sensore;
  pinMode(triggerPin, OUTPUT); // Clear the trigger
  digitalWrite(triggerPin, LOW);
  delayMicroseconds(2);
  // Sets the trigger pin to HIGH state for 10 microseconds
  digitalWrite(triggerPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(triggerPin, LOW);
  pinMode(echoPin, INPUT);
  // measure the ping time in cm
  int cm = 0.01723 * pulseIn(echoPin, HIGH);
  if (cm <=100) { stato_sensore= 1; } else { stato_sensore= 0; }
  return stato_sensore;
}

```